

Product Specification

Product: Laser Partical Sensor

Product model: PMS7003T

Specification No.: PTQ3023-2017

Version: V1.0

| Writer | Verifier | Standardization | Approver |
|---------------|--------------|-----------------|-----------|
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| 2019-2-20 | 2019-2-20 | 2019-2-20 | 2019-2-20 |



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| Version | Note | Date | Writer |
|---------|-------------|-----------|---------|
| V1.0 | Newly-built | 2019.2.20 | Lu Lili |
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1. Main characteristics

- Zero false alarm rate
- Real-time response
- ◆ Correct data



- ◆ Minimum distinguishable particle diameter :0.3 micrometer
- High anti-interference performance because of the structure of six sides shielding
- Ultra-thin and ultra-small design, only 12 mm
- ◆ Temperature and humidity output

2. Overview

PMS7003T is a kind of digital and universal particle concentration sensor, which can be used to obtain the number of suspended particles in the air, i.e. the concentration of particles, it also integrates in it an one-chip sensor for temperature and humidity. and output them in the form of digital interface. This sensor can be inserted into variable instruments related to the concentration of suspended particles in the air or other environmental improvement equipments to provide correct concentration data in time.



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3. Working principle

Laser scattering principle is used for such sensor, i.e. produce scattering by using laser to radiate suspending particles in the air, then collect scattering light in a certain degree, and finally obtain the curve of scattering light change with time. In the end, equivalent particle diameter and the number of particles with different diameter per unit volume can be calculated by microprocessor based on MIE theory. Please find the functional diagram of each part of sensor from Figure 1 as follows.

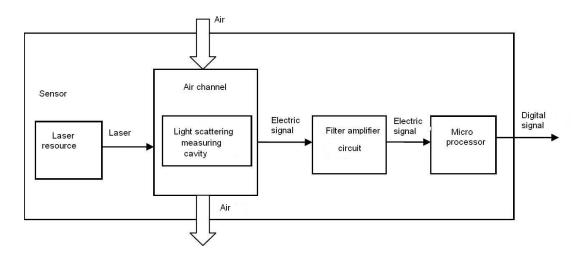


Figure 1 Functional block diagram of sensor

4. Technical Index

| Parameter | Index | unit |
|---|--------------------------|-----------------|
| Particle Range of measurement | 0.3~1.0; 1.0~2.5; 2.5~10 | Micrometer (µm) |
| Particle Counting Efficiency | 50%@0.3μm 98%@>=0.5μm | |
| Particle Effective Range (PM2.5 standard) | 0~500 | μg/m³ |
| Particle Maximum Range | ≥1000 | μg/m³ |



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| Particle Resolution | 1 | μg/m³ |
|---------------------------|--------------------------|-------------------|
| Particle Maximum | ±10%@100~500µg/m³ | |
| Consistency Error (PM2.5 | ±10µg/m³@0~100µg/m³ | |
| standard data)* | | |
| Particle Standard Volume | 0.1 | Litre (L) |
| Temperature Range | 0~99 | ${\mathbb C}$ |
| Temperature Resolution | 0.1 | $^{\circ}$ C |
| Humidity Range | 0~99 | % |
| Humidity Resolution | 0.1 | % |
| Single Response Time | <1 | Second (s) |
| Total Response Time | ≤10 | Second (s) |
| DC Power Supply | Typ:5.0 Min:4.5 Max: 5.5 | Volt (V) |
| Active Current | ≤100 | Milliampere (mA) |
| Standby Current | ≤200 | Milcroampere (uA) |
| Interface Level | L <0.8 @3.3 H >2.7@3.3 | Volt (V) |
| Working Temperature | -10~+60 | °C |
| Range | | <u></u> |
| Working Humidity Range | 0~99% | |
| Storage Temperature Range | -40~+80 | °C |
| MTTF | ≥3 | Year(Y) |
| Physical Size | 48×37×12 | Millimeter (mm) |

Note 1: Maximum range means that the highest output value of the PM2.5 standard data is not less than 1000.



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Note 2: "PM2.5 standard data" is the "data2" in the appendix.20°C, 50%.

5. Output result

- 1) Mainly output as the quality and number of each particles with different size per unit volume, the unit volume of particle number is 0.1L and the unit of mass concentration is µg/m³.
- 2) There are two options for digital output: passive and active. Default mode is active after power up. In this mode sensor would send serial data to the host automatically. The active mode is divided into two submodes:stable mode and fast mode. If the concentration change is small the sensor would run at stable mode with the real interval of 2s.And if the change is big the sensor would be changed to fast mode automatically with the interval of 200~800ms, the higher of the concentration, the shorter of the interval.

6. Pin Definition

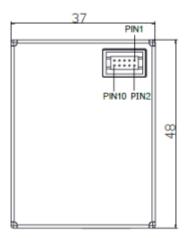


Figure 2 Connector Definition



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| Pin number | Pin name | Description | |
|------------|----------|---|--|
| PIN1 | VCC | Positive power 5V | |
| PIN2 | VCC | Positive power 5V | |
| PIN3 | GND | Negative power | |
| PIN4 | GND | Negative power | |
| PIN5 | RESET | Module reset signal/TTL level@3.3V, low reset | |
| PIN6 | NC | | |
| PIN7 | RXD | Serial port receiving pin/TTL level@3.3V | |
| PIN8 | NC | | |
| PIN9 | TXD | Serial port sending pin/TTL level@3.3V | |
| PIN10 | SET | Set pin/TTL level @3.3V, high level or | |
| | | suspending is normal working status, while | |
| | | low level is sleeping mode. | |

7. Typical Circuit

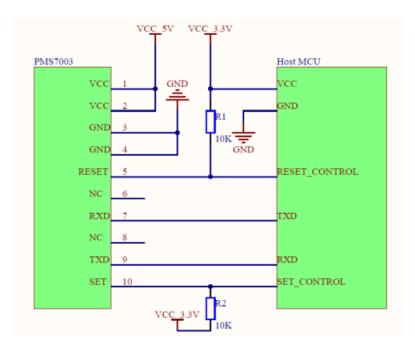


Figure 3 Typical Circuit



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8. Circuit Attentions

- DC 5V power supply is needed because the FAN should be driven by
 5V. But the high level of data pin is 3.3V. Level conversion unit should be used if the power of host MCU is 5V.
- The SET and RESET pins are pulled up inside so they should not be connected if without usage.
- 3) PIN6 and PIN8 should not be connected.
- 4) Stable data should be got at least 30 seconds after the sensor wakeup from the sleep mode because of the fan's performance.

9. Typical Output Characteristic

Definition of axis Y: PM2.5 concentration, unit: µg/m³

Definition of axis X: number of samples, unit: time

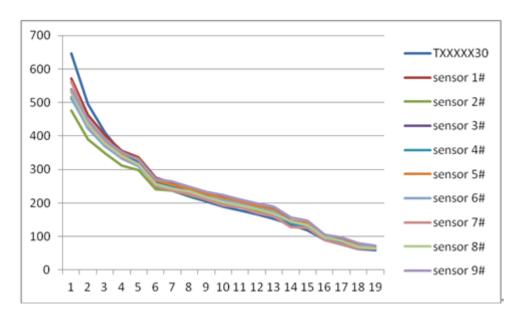


Figure 4-1 Consistency at 20°C



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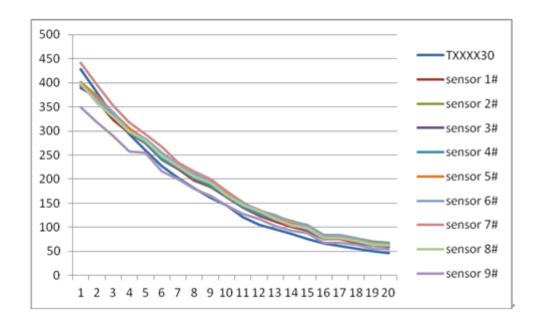


Figure 4-2 Consistency at 43°C

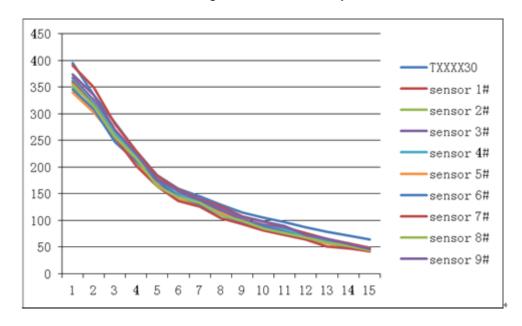


Figure 4-3 Consistency at -5°C



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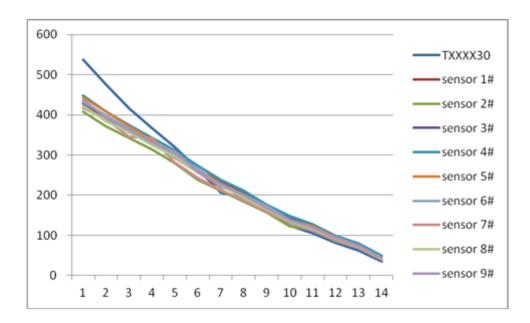


Figure 4-4 Consistency after 30 days running

Relationship of Temperature and Consistency

Definition of axis Y: Maximum Error Modulus(%)

Definition of axis X: Temperature ($^{\circ}$ C)

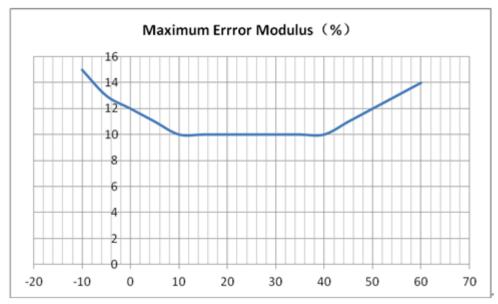


Figure 5 Consistency Vs Temperature

| PLA | TNA | OW. | /ER |
|-----|-----|-----|----------|
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10. Endurance Characteristics

| No | Item | Test Method | | Characteristics | n |
|----|----------------|-------------|--|-------------------|------|
| 4 | | _ | 40 1 | 40 1 1 | C |
| 1 | Long Running | 1. | 10 m² closed Lab, 20~25 °C , | 10 samples during | n=30 |
| | | | humidity 30%~70%, particle | 0~500μg/m³ | C=0 |
| | | | generator and air cleaner | | |
| | | 2. | DC 5V power supply | 0~100μg/m³ | |
| | | 3. | Check consistency after 720 | Maximum | |
| | | | hours' running | Error≤±15μg/m³ | |
| 2 | High | 1. | 10 m^{2} constant temperature Lab | | n=10 |
| | Temperature | 2. | 43 $^{\circ}$ C ,humidity 70%, | 100~500μg/m³ | C=0 |
| | Operation | 3. | particle generator and air cleaner | Maximum | |
| | | 4. | DC 5V power supply | Error≤±15% | |
| | | 5. | Check consistency | | |
| 3 | Cold Operation | 1. | 10 m² constant temperature Lab | | n=10 |
| | | 2. | -5 $^{\circ}$ C $^{\circ}$, humidity 30% $^{\circ}$ | FAN does not | C=0 |
| | | 3. | particle generator and air cleaner | screeched | |
| | | 4. | DC 5V power supply | | |
| | | 5. | Check consistency | | |
| 4 | Vibration | 1. | 10 m² closed Lab, , 20 °C , | | n=5 |
| | | | humidity 50%, particle | | C=0 |
| | | | generator and air cleaner | | |
| | | 2. | DC 5V power supply and check | | |
| | | | consistency | | |
| | | 3. | Frequency: 50Hz. | | |
| | | 4. | acceleration: 9.8/ S ² 。 | | |
| | | 5. | Direction: X, Y, Z | | |
| | | 6. | Vibration Amplitude: ±2mm. | | |
| | | 7. | Time: X、Y、Z—way, Per 1 hour | | |
| 5 | High | 1. | Constant temperature cabinet | 10 samples during | n=10 |
| | Temperature | 2. | 70°C,humidity 90%~95, | 0~500μg/m³ | C=0 |
| | and Humidity | 3. | Check consistency after 500 | | |
| | Storage | | urs' storage | 0~100μg/m³ | |
| 6 | Cold Storage | 1. | Constant temperature cabinet | Maximum | n=10 |
| | 30.0 3.0.06 | 2. | -30°C, humidity 90%~95, | Error≤±10μg/m³ | C=0 |
| | | 3. | Check consistency after 500 | | |
| | | | urs' storage | 100~500μg/m³ | |
| | | | 213 313146 | | |

| PL/ | TNA | OV | /ER |
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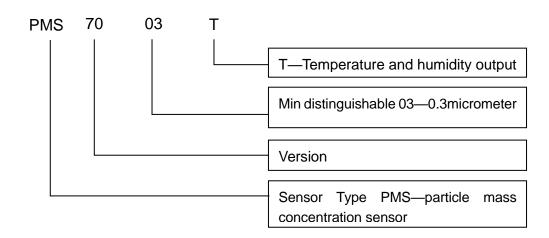
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| _ | 1 | | | | | |
|--------------|---------------|-----|---|---------------|-----|------|
| 7 | Variation of | 4. | 10 M^2 closed Lab, 20°C , | Maximum | | n=5 |
| Power Supply | | | humidity 50%,particle | Error≤±10% | | C=0 |
| | | | generator and air cleaner | | | |
| | | 5. | Power varies as the cycles of 4.5V | | | |
| | | | to 5.5V ,then 5.5V to 4.5V with the | FAN does | not | |
| | | | pace of 0.1V/min for 2 hours. | screeched | | |
| | | 6. | Check consistency during | | | |
| | | | Variation | | | |
| 8 | Power On-Off | 1. | 10 M^{2} closed Lab, , 20 $^{\circ}\text{C}$, | | | n=10 |
| | Cycle | | humidity 50%,particle | | | C=0 |
| | | | generator and air cleaner | | | |
| | | 2. | DC 5V power supply, keep On- | | | |
| | | | Off frequency 0.5Hz for 72 hours | | | |
| | | | and check consistency | | | |
| 9 | Sleep Set On- | 1. | 10 M^2 closed Lab, 20°C , | | | n=10 |
| | Off | | humidity 50%, particle | | | C=0 |
| | Cycle | | generator and air cleaner | | | |
| | | 2. | DC 5V power supply, keep Sleep | | | |
| | | | Set Pin High-Low frequency 0.5Hz | | | |
| | | | for 72 hours and check | | | |
| | | | consistency | | | |
| 10 | Laser On-Off | 1. | 10 M^2 closed Lab, 20°C , | | | n=10 |
| | Cycle | | humidity 50%, particle | | | C=0 |
| | | | generator and air cleaner | | | |
| | | 2. | keep laser On-Off frequency | | | |
| | | | 50Hz for 240 hours and check | | | |
| | | | consistency | | | |
| 11 | Salt Spray | 5% | industrial salt water, hydrolysis | No rust | and | n=1 |
| | | spr | ay 100 hours, clean with purified | discoloration | of | C=0 |
| | | wa | ter and store for 48 hours | metal parts | | |
| | | | · · · · · · · · · · · · · · · · · · · | | | |



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11. Part Number Definition

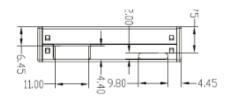


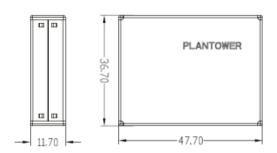
| PLA | TNA | OW. | /ER |
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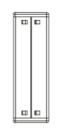
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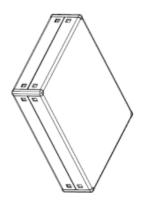
12. Physical Size

(Unit:mm)

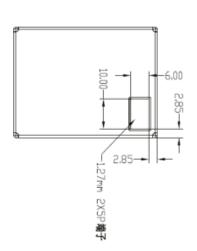


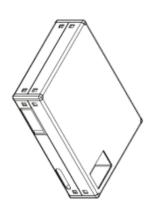














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13. Installation Attentions

- Metal shell is connected to the GND so be careful not to let it shorted with the other parts of circuit except GND.
- 2) The best way of install is making the plane of inlet and outlet closely to the plane of the host. Or some shield should be placed between inlet and outlet in order to prevent the air flow from inner loop.
- 3) The blowhole in the shell of the host should not be smaller than the inlet.
- 4) The sensor should not be installed in the air flow way of the air cleaner or should be shielded by some structure.
- 5) The sensor should be installed at least 20cm higher than the grand in order to prevent it from blocking by the flock dust.
- 6) When the sensor is used to outdoor fixed equipment, the equipment should be completed for the protection of sandstorm, rain, snow, etc.
- 7) Do not break up the sensor.

14. Other Attentions

- Only the consistency of all the PM sensors of PLANTOWER is promised and ensured. And the sensor should not be checked with any third party equipment.
- 2) The sensor is usually used in the common indoor environment. So some protection must be added if using in the conditions as followed:
 - a) The time of concentration ≥300μg/m³ is longer than 50% of the whole year or concentration≥500μg/m³ is longer than 20% of the whole year.
 - b) Kitchen

| PLANTOWER | | | | | | |
|-----------|---|--|--|--|--|--|
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- c) Water mist condition such as bathroom or hot spring.
- d) Outdoor

15. Appendix I: transport protocol Active Mode

Default baud rate: 9600bps Check bit: None Stop bit: 1 bit

32 Bytes

| 02 By100 | | |
|--------------------------|------|--|
| Start character 1 | 0x42 | (Fixed) |
| Start character2 | 0x4d | (Fixed) |
| Frame length high 8 bits | | Frame length=2x13+2(data+check bytes) |
| Frame length low 8 bits | | |
| Data 1 high 8 bits | | Data1 refers to PM1.0 concentration unit µ |
| Data 1 low 8 bits | | g/m3 (CF=1, standard particle) * |
| Data2 high 8 bits | | |
| Data2 low 8 bits | | g/m3 (CF=1, standard particle) |
| Data3 high 8 bits | | Data3 refers to PM10 concentration unit μ |
| Data3 low 8 bits | | g/m3 (CF=1, standard particle) |
| Data4 high 8 bits | | Data4 refers to PM1.0 concentration unit * µ |
| Data4 low 8 bits | | g/m3 (under atmospheric environment) |
| Data5 high 8 bits | | Data 5 refers to PM2.5 concentration unit µ |
| Data5 low 8 bits | | g/m3 (under atmospheric environment) |
| Data6 high 8 bits | | Data 6 refers to concentration unit (under |
| Data6 low 8 bits | | atmospheric environment) µ g/m3 |
| Data7 high 8 bits | | Data7 indicates the number of particles with diameter beyond 0.3 um in 0.1 L of air. |



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| Data7 low 8 bits | |
|---------------------------|--|
| Data8 high 8 bits | Data 8 indicates the number of particles |
| Data8 low 8 bits | with diameter beyond 0.5 um in 0.1 L of air. |
| Data9 high 8 bits | Data 9 indicates the number of particles |
| Data9 low 8 bits | with diameter beyond 1.0 um in 0.1 L of air. |
| Data10 high 8 bits | Data10 indicates the number of particles |
| Data10 low 8 bits | with diameter beyond 2.5 um in 0.1 L of air. |
| Data11 high 8 bits | Temperature = Data11(signed)/10 |
| Data11 low 8 bits | Unit:°C |
| Data12 high 8 bits | Humidity = Data12(signed)/10 |
| Data12 low 8 bits | Unit:% |
| Data13 high 8 bits | Version |
| Data13 low 8 bits | error code |
| Data and check high | Check code=Start character1+ Start character |
| 8 bits | 2++data 13 I ow 8 bits |
| Data and check low 8 bits | |

Note: CF=1 should be used in the factory environment

16. Appendix II: transport protocol Passive Mode

Default baud rate: 9600bps Check bit: None Stop bit: 1 bit

1) Host Protocol

| Start Byte | Start Byte | Command | Data 1 | Data 2 | Verify | Verify |
|------------|------------|---------|--------|--------|--------|--------|
| 1 | 2 | | | | Byte 1 | Byte 2 |
| 0x42 | 0x4d | CMD | DATAH | DATAL | LRCH | LRCL |



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2) Command Definition

| CMD | DATAH | DATAL | Note |
|------|-------|-------------|-----------------|
| 0xe2 | Х | X | Read in passive |
| | | | mode |
| 0xe1 | Х | 00H-passive | Change mode |
| | | 01H-active | |
| 0xe4 | Х | 00H-sleep | Sleep set |
| | | 01H-wakeup | |

3) Answer

a) 0xe2: 32bytes, same as appendix I

b) 0xe1:

| Start | Start | Frame | Frame | Command | Data | Verify | Verify |
|--------|--------|---------|---------|---------|------|--------|--------|
| Byte 1 | Byte 2 | length1 | length2 | | | Byte 1 | Byte 2 |
| 0x42 | 0x4d | 0x00 | 0x04 | 0xe1 | work | LRCH | LRCL |

c) 0xe4:

| Start | Start | Frame | Frame | Command | Data | Verify | Verify |
|--------|--------|---------|---------|---------|-------|--------|--------|
| Byte 1 | Byte 2 | length1 | length2 | | | Byte 1 | Byte 2 |
| 0x42 | 0x4d | 0x00 | 0x04 | 0xe4 | sleep | LRCH | LRCL |

4) Verify Bytes:

Add of all the bytes except verify bytes.